

# ON SOME PERTURBATIONS OF A SYMMETRIC STABLE PROCESS AND THE CORRESPONDING CAUCHY PROBLEMS

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ABSTRACT. A semigroup of linear operators on the space of all continuous bounded functions given on a  $d$ -dimensional Euclidean space  $\mathbb{R}^d$  is constructed such that its generator can be written in the following form  $\mathbf{A} + (a(\cdot), \mathbf{B})$ , where  $\mathbf{A}$  is the generator of a symmetric stable process in  $\mathbb{R}^d$  with the exponent  $\alpha \in (1, 2]$ ,  $\mathbf{B}$  is the operator that is determined by the equality  $\mathbf{A} = c \operatorname{div}(\mathbf{B})$  ( $c > 0$  is a given parameter), and a given  $\mathbb{R}^d$ -valued function  $a \in L_p(\mathbb{R}^d)$  for some  $p > d + \alpha$  (the case of  $p = +\infty$  is not exclusion). However, there is no Markov process in  $\mathbb{R}^d$  corresponding to this semigroup because it does not preserve the property of a function to take on only non-negative values. We construct a solution of the Cauchy problem for the parabolic equation  $\frac{\partial u}{\partial t} = (\mathbf{A} + (a(\cdot), \mathbf{B}))u$ .

## INTRODUCTION

A  $d$ -dimensional symmetric stable process ( $\alpha$ -stable process) is a Markov process in  $\mathbb{R}^d$  with its transition probability density given by

$$g(t, x, y) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} \exp \{i(y - x, \xi) - ct|\xi|^\alpha\} d\xi, \quad t > 0, \quad x \in \mathbb{R}^d, \quad y \in \mathbb{R}^d$$

(parameters  $c > 0$  and  $\alpha \in (1, 2]$  will be fixed throughout this article). As is well known, the generator  $\mathbf{A}$  of this process is a pseudo-differential operator, whose symbol is given by the expression  $(-c|\lambda|^\alpha)_{\lambda \in \mathbb{R}^d}$ . The parameter  $\alpha$  is called the exponent of this process.

A Wiener process is a particular case of a symmetric stable process, if we put  $\alpha = 2$  and  $c = 1/2$ . Its generator is the Laplace operator (with the multiplier  $1/2$ ). The perturbation of this operator by means of the operator  $(a, \nabla)$ , where  $(a(x))_{x \in \mathbb{R}^d}$  is some  $\mathbb{R}^d$ -valued function,  $\nabla$  is the Hamilton operator (gradient) and  $(\cdot, \cdot)$  denotes the scalar product in  $\mathbb{R}^d$ , allows us to construct the diffusion process with the drift vector  $a$ . A great deal of publications considered perturbations under some more or less general assumptions on the function  $a$  (see, for example, [5] and the references therein).

This article is devoted to the perturbing a symmetric stable process with  $\alpha \in (1, 2)$  in a similar way. In our situation the operator  $\mathbf{B}$ , with its symbol  $(i|\lambda|^{\alpha-2}\lambda)_{\lambda \in \mathbb{R}^d}$ , is an analogue to the gradient. The role of this operator in the theory of potentials for symmetric stable processes is discussed in the paper [9].

Symmetric stable processes were perturbed by terms of the type  $(a, \nabla)$  under various assumptions on the function  $a$  in many papers (see, for example, [2, 4, 10, 11]). The perturbation of stable processes with delta-function in coefficient is constructed in [6, 8]. The operator  $\mathbf{B}$  used in perturbations of stable processes in the papers [6, 7, 8].

This paper is organized as follows. In the next section we present the basic concepts and preliminary results. Section 2 contains the construction of the stable process perturbation and the investigation of some its properties. And the final Section 3 is devoted to the Cauchy problem for the pseudo-differential equation of parabolic type with operator  $\mathbf{A} + (a, \mathbf{B})$  on the spatial variable.

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## 1. NOTATION AND AUXILIARY RESULTS

Let  $F_\gamma$  ( $\gamma > 0$ ) be the class of functions  $\varphi(x)$  defined on  $\mathbb{R}^d$  with values in  $\mathbb{R}$ , which are the Fourier transforms  $\varphi(x) = \int_{\mathbb{R}^d} e^{i(x,\lambda)} \Phi(\lambda) d\lambda$  and such that the functions  $|\lambda|^\gamma \Phi(\lambda)$  are absolutely integrable on  $\mathbb{R}^d$ .

Recall that the operator  $\mathbf{A}$  acting on the functions  $\varphi \in F_\alpha$  according to the following rule  $\mathbf{A}\varphi(x) = -c \int_{\mathbb{R}^d} |\lambda|^\alpha e^{i(x,\lambda)} \Phi(\lambda) d\lambda$  and the equality  $\mathbf{B}\varphi(x) = \int_{\mathbb{R}^d} i|\lambda|^{\alpha-2} \lambda e^{i(x,\lambda)} \Phi(\lambda) d\lambda$  is true for functions  $\varphi \in F_{\alpha-1}$ . It is easy to see that the equality  $\mathbf{A} = c \operatorname{div}(\mathbf{B})$  holds on  $F_{\alpha-1}$ , where  $\operatorname{div}$  is the divergence operator.

Let  $(a(x))_{x \in \mathbb{R}^d}$  be a some given  $\mathbb{R}^d$ -valued measurable function.

**Definition 1.1.** A function  $(G(t, x, y))_{t>0, x \in \mathbb{R}^d, y \in \mathbb{R}^d}$  is called a result of perturbing the transition probability density  $g(t, x, y)$ , if it is a solution of the following equation

$$(1) \quad G(t, x, y) = g(t, x, y) + \int_0^t d\tau \int_{\mathbb{R}^d} g(t - \tau, x, z) (a(z), \mathbf{B}_z G(\tau, z, y)) dz.$$

The subscript of operator  $\mathbf{B}$  (here and in what follows) means that it acts on a function of several variables in the indicated variable.

We will construct the solution of equality (1) in the form

$$(2) \quad G(t, x, y) = g(t, x, y) + \int_0^t d\tau \int_{\mathbb{R}^d} g(t - \tau, x, z) V(\tau, z, y) |a(z)| dz,$$

where the function  $V(t, x, y)$  satisfies the equation

$$(3) \quad V(t, x, y) = V_0(t, x, y) + \int_0^t d\tau \int_{\mathbb{R}^d} V_0(t - \tau, x, z) V(\tau, z, y) |a(z)| dz$$

and

$$(4) \quad V_0(t, x, y) = (\mathbf{B}_x g(t, x, y), e(x)) = \frac{1}{c\alpha} \frac{(y - x, e(x))}{t} g(t, x, y).$$

Here we use a function  $(e(x))_{x \in \mathbb{R}^d}$  defined by the equality  $e(x) = \frac{1}{|a(x)|} a(x)$  for  $x \in \mathbb{R}^d$  such that  $|a(x)| \neq 0$  and an arbitrary value (with preservation of the measurability) otherwise.

Equation (3) can be solved by the method of successive approximations, namely its solution will be found in the form

$$(5) \quad V(t, x, y) = \sum_{k=0}^{\infty} V_k(t, x, y),$$

where  $V_0(t, x, y)$  is defined by equality (4) and for  $k \geq 1$  the following equality

$$V_k(t, x, y) = \int_0^t d\tau \int_{\mathbb{R}^d} V_0(t - \tau, x, z) V_{k-1}(\tau, z, y) |a(z)| dz$$

is valid.

We will use some inequalities that are proved in the article [3].

The first inequality is

$$(6) \quad g(t, x, y) \leq N \frac{t}{(t^{1/\alpha} + |y - x|)^{d+\alpha}},$$

where  $N > 0$  is a constant,  $t > 0$ ,  $x \in \mathbb{R}^d$ ,  $y \in \mathbb{R}^d$ .

The following inequality will be used in various situations

$$(7) \quad \int_0^t d\tau \int_{\mathbb{R}^d} \frac{(t-\tau)^{\beta/\alpha}}{((t-\tau)^{1/\alpha} + |z-x|)^{d+\alpha+k}} \frac{\tau^{\gamma/\alpha}}{(\tau^{1/\alpha} + |y-z|)^{d+\alpha+l}} dz \leq \\ \leq C \left[ B\left(\frac{\beta-k}{\alpha}, 1 + \frac{\gamma}{\alpha}\right) t^{\frac{\beta+\gamma-k}{\alpha}} \frac{1}{(t^{1/\alpha} + |y-x|)^{d+\alpha+l}} + \right. \\ \left. + B\left(1 + \frac{\beta}{\alpha}, \frac{\gamma-l}{\alpha}\right) t^{\frac{\beta+\gamma-l}{\alpha}} \frac{1}{(t^{1/\alpha} + |y-x|)^{d+\alpha+k}} \right],$$

that is true for some constants  $\beta, \gamma, k, l$ , satisfying the conditions:  $-\alpha < k < \beta$ ,  $-\alpha < l < \gamma$ , and  $C > 0$  which depends only on  $d, \alpha, k$  and  $l$ . Here  $B(\cdot, \cdot)$  is Euler beta function.

We shall also use below the following result (see, for example, [3]). Denote by  $C_b(D)$  the space of all continuous bounded real-valued functions on the set  $D$ . Let  $\varphi \in C_b(\mathbb{R}^d)$  and  $(f(t, x))_{t \geq 0, x \in \mathbb{R}^d}$  be a continuous function bounded on each domain of the form  $D_T = [0, T] \times \mathbb{R}^d$  for  $T < +\infty$ . We suppose that the function  $f$  is Hölder continuous (with an arbitrary coefficient from the interval  $(0, 1)$ ) in the argument  $x$  locally uniformly with respect to  $t$ . Then the unique bounded solution of the Cauchy problem

$$(8) \quad \begin{cases} \frac{\partial u(t, x)}{\partial t} = \mathbf{A}_x u(t, x) + f(t, x), & t > 0, x \in \mathbb{R}^d, \\ \lim_{t \rightarrow 0+} u(t, x) = \varphi(x), & x \in \mathbb{R}^d \end{cases}$$

can be written as follows

$$u(t, x) = \int_{\mathbb{R}^d} g(t, x, y) \varphi(y) dy + \int_0^t d\tau \int_{\mathbb{R}^d} g(t-\tau, x, z) f(\tau, z) dz.$$

## 2. THE PERTURBATION

In this section we will prove existence of the perturbation (in the sense of Definition 1.1) by operator  $\mathbf{B}$  with the function  $a$  satisfies some integrability condition. A few properties of this perturbation will be established below.

**Theorem 2.1.** *Let the function  $(a(x))_{x \in \mathbb{R}^d}$  satisfies the following condition:  $a \in L_p(\mathbb{R}^d)$  with  $p > d + \alpha$  (maybe,  $p = +\infty$ ).*

*Then the perturbation  $G(t, x, y)$  (see Definition 1.1) exists and possesses the following properties*

- (i) *It satisfies the Kolmogorov-Chapman equation*

$$\int_{\mathbb{R}^d} G(t, x, z) G(s, z, y) dz = G(t+s, x, y), \quad t > 0, s > 0, x \in \mathbb{R}^d, y \in \mathbb{R}^d;$$

- (ii) *It is absolutely integrable and  $\int_{\mathbb{R}^d} G(t, x, y) dy \equiv 1$ .*

*Proof.* Formulas (4), (6), and (7) allows us to write down the inequality

$$(9) \quad |V_0(t, x, y)| \leq \frac{N}{c\alpha} \frac{1}{(t^{1/\alpha} + |y-x|)^{d+\alpha-1}}$$

Then the following inequality is true for all  $k \in \mathbb{N}$  and  $t > 0, x \in \mathbb{R}^d, y \in \mathbb{R}^d$

$$|V_k(t, x, y)| \leq \frac{N}{c\alpha} \int_0^t d\tau \int_{\mathbb{R}^d} \frac{1}{((t-\tau)^{1/\alpha} + |z-x|)^{d+\alpha-1}} |V_{k-1}(\tau, z, y)| |a(z)| dz$$

Using inequality (7) one can show by induction on  $k$  that the function  $V_k$  for  $k = 0, 1, 2, \dots$  satisfies the inequality

$$\begin{aligned} |V_k(t, x, y)| &\leq \|a\|_p^k \left(\frac{N}{c\alpha}\right)^{k+1} C^{k\nu} R_k \frac{t^{k\frac{\rho}{\alpha}}}{(t^{1/\alpha} + |y-x|)^{d+\alpha-1}} \leq \\ &\leq \|a\|_p^k \left(\frac{N}{c\alpha}\right)^{k+1} C^{k\nu} R_k t^{(k\rho-d+1)\frac{1}{\alpha}-1}, \end{aligned}$$

where  $\nu = 1 - \frac{1}{p}$ ,  $\rho = 1 - \frac{d}{p}$ ,  $R_0 = 1$ ,  $R_k = R_{k-1} \left( B \left( \frac{p-d-\alpha}{\alpha(p-1)}, 1 + (k-1)\frac{p-d}{\alpha(p-1)} \right) + B \left( 1, \frac{p-d-\alpha}{\alpha(p-1)} + (k-1)\frac{p-d}{\alpha(p-1)} \right) \right)^{1-\frac{1}{p}}$  (or limits of these expressions when  $p$  tends to infinity, if  $p = +\infty$ ).

Therefore, the series on the right hand side of (5) converges uniformly in  $x \in \mathbb{R}^d$ ,  $y \in \mathbb{R}^d$  and locally uniformly in  $t > 0$ . Thus, the function  $V$  given by this equality is a solution of equation (3). In addition, the following inequality

$$(10) \quad |V(t, x, y)| \leq C_T \frac{1}{(t^{1/\alpha} + |y-x|)^{d+\alpha-1}}$$

has been proved for  $x \in \mathbb{R}^d$ ,  $y \in \mathbb{R}^d$  and  $0 < t \leq T$ , where  $C_T$  is a positive constant that, maybe, depends on  $T > 0$ .

*Remark 2.1.* The function  $V(t, x, y)$  is the unique solution of equation (3) in the class of functions that satisfy inequality (10).

Finally, since the equality  $(\mathbf{B}_x G(t, x, y), e(x)) = V(t, x, y)$  holds, the function

$$(11) \quad G(t, x, y) = g(t, x, y) + \int_0^t d\tau \int_{\mathbb{R}^d} g(t-\tau, x, z) V(\tau, z, y) |a(z)| dz,$$

is the perturbation of the transition probability density of the  $\alpha$ -stable process.

Here we have used the following statement.

**Lemma 2.1.** *The equality  $\mathbf{B}_x \int_0^t d\tau \int_{\mathbb{R}^d} g(t-\tau, x, z) V(\tau, z, y) |a(z)| dz = \int_0^t d\tau \int_{\mathbb{R}^d} \mathbf{B}_x g(t-\tau, x, z) V(\tau, z, y) |a(z)| dz$  is true.*

The proof of this lemma is based on the following representation of the operator  $\mathbf{B}$ :

$$\mathbf{B}\varphi(x) = \frac{1}{\varkappa} \int_{\mathbb{R}^d} \frac{\varphi(x+y) - \varphi(x)}{|y|^{d+\alpha}} y dy \text{ for a bounded differentiable function } (\varphi(x))_{x \in \mathbb{R}^d},$$

where  $\varkappa = -\frac{2\pi^{\frac{d-1}{2}} \Gamma(2-\alpha) \Gamma(\frac{\alpha+1}{2}) \cos \frac{\pi\alpha}{2}}{(\alpha-1) \Gamma(\frac{d+\alpha}{2})}$ .

*Proof.* Let us consider a set of operators  $\{\mathbf{B}^\varepsilon : \varepsilon > 0\}$  that act on a continuously differentiable bounded function  $(\varphi(x))_{x \in \mathbb{R}^d}$  according to the following rule

$$\mathbf{B}^\varepsilon \varphi(x) = \frac{1}{\varkappa} \int_{|u| \geq \varepsilon} \frac{\varphi(x+u) - \varphi(x)}{|u|^{d+\alpha}} y dy.$$

It is clear that  $\lim_{\varepsilon \rightarrow 0^+} \mathbf{B}^\varepsilon \varphi(x) = \mathbf{B}\varphi(x)$  for all  $x \in \mathbb{R}^d$  and described above functions  $\varphi$ .

Inequalities (6) and (10) allow us to assert that

$$\begin{aligned} & \left| \frac{u}{|u|^{d+\alpha}} (g(t-\tau, x+u, z) - g(t-\tau, x, z)) V(\tau, z, y) |a(z)| \right| \leq \\ & \leq \frac{\text{const}}{|u|^{d+\alpha-1}} \left( \frac{t-\tau}{((t-\tau)^{1/\alpha} + |z-x-u|)^{d+\alpha}} + \frac{t-\tau}{((t-\tau)^{1/\alpha} + |z-x|)^{d+\alpha}} \right) \times \\ & \quad \times \frac{1}{(\tau^{1/\alpha} + |y-z|)^{d+\alpha-1}}. \end{aligned}$$

It is easy to see that the right hand side of this inequality is an integrable function with respect to  $(u, \tau, z)$  on the set  $\{|u| \geq \varepsilon\} \times (0; t) \times \mathbb{R}^d$  for all  $t > 0$  and  $x \in \mathbb{R}^d, y \in \mathbb{R}^d$ . Here we used formula (7). Therefore, we obtain the following equality

$$(12) \quad \begin{aligned} \mathbf{B}_x^\varepsilon \int_0^t d\tau \int_{\mathbb{R}^d} g(t-\tau, x, z) V(\tau, z, y) |a(z)| dz &= \\ &= \int_0^t d\tau \int_{\mathbb{R}^d} \mathbf{B}_x^\varepsilon g(t-\tau, x, z) V(\tau, z, y) |a(z)| dz, \end{aligned}$$

using Fubini's theorem.

Inequalities (6), (7) and  $|\mathbf{B}_x g(t, x, y)| \leq \frac{\text{const}}{(t^{1/\alpha} + |y-x|)^{d+\alpha-1}}$  allow us to assert that the integral  $\int_0^t d\tau \int_{\mathbb{R}^d} \mathbf{B}_x g(t-\tau, x, z) V(\tau, z, y) |a(z)| dz$  exists. Now we have to pass to the limit as  $\varepsilon \rightarrow 0+$  in equality (12) to complete the proof of lemma.  $\square$

Let us prove that the function  $G(t, x, y)$  satisfies the Kolmogorov-Chapman equation

$$(13) \quad G(t+s, x, y) = \int_{\mathbb{R}^d} G(s, x, z) G(t, z, y) dz$$

for all  $s > 0, t > 0, x \in \mathbb{R}^d, y \in \mathbb{R}^d$ . Note, that the function  $g(t, x, y)$  satisfies equation (13).

Put  $U(s, x, \varphi) = \int_{\mathbb{R}^d} G(s, x, y) \varphi(y) dy, \quad u(s, x, \varphi) = \int_{\mathbb{R}^d} g(s, x, y) \varphi(y) dy, \quad \text{and}$   
 $W(s, x, \varphi) = \int_{\mathbb{R}^d} V(s, x, y) \varphi(y) dy, \text{ where } \varphi \in C_b(\mathbb{R}^d).$

Note, that the function  $W(t, x, \varphi)$  is the unique solution of the following equation

$$(14) \quad W(t, x, \varphi) = W_0(t, x, \varphi) + \int_0^t d\tau \int_{\mathbb{R}^d} V_0(t-\tau, x, z) W(\tau, z, \varphi) |a(z)| dz,$$

where  $W_0(s, x, \varphi) = \int_{\mathbb{R}^d} V_0(s, x, y) \varphi(y) dy.$

Then the function  $U(s, x, \varphi)$  can be given by the equality (see (11))

$$U(t, x, \varphi) = u(t, x, \varphi) + \int_0^t d\tau \int_{\mathbb{R}^d} g(t-\tau, x, z) W(\tau, z, \varphi) |a(z)| dz$$

Now, let us find the function  $U(t+s, x, \varphi)$ . We have

$$\begin{aligned} U(t+s, x, \varphi) &= u(t+s, x, \varphi) + \int_0^{t+s} d\tau \int_{\mathbb{R}^d} g(t+s-\tau, x, z) W(\tau, z, \varphi) |a(z)| dz = \\ &= \int_{\mathbb{R}^d} g(s, x, y) u(t, y, \varphi) dy + \int_{\mathbb{R}^d} g(s, x, y) dy \int_0^t d\tau \int_{\mathbb{R}^d} g(t-\tau, y, z) W(\tau, z, \varphi) |a(z)| dz + \\ & \quad + \int_t^{s+t} d\tau \int_{\mathbb{R}^d} g(t+s-\tau, x, z) W(\tau, z, \varphi) |a(z)| dz = \\ &= \int_{\mathbb{R}^d} g(s, x, y) U(t, y, \varphi) dy + \int_0^s d\tau \int_{\mathbb{R}^d} g(s-\tau, x, z) W(t+\tau, z, \varphi) |a(z)| dz. \end{aligned}$$

Therefore, the function  $W_t(s, x, \varphi) = W(t + s, x, \varphi)$  satisfies equation (14), where the function  $\varphi$  is replaced by  $U(t, \cdot, \varphi)$ . Then  $W(t + s, x, \varphi) = W(s, x, U(t, \cdot, \varphi))$  and we arrive at the equality  $U(t + s, x, \varphi) = U(s, x, U(t, \cdot, \varphi))$  or, what is the same,

$$\begin{aligned} \int_{\mathbb{R}^d} G(t + s, x, y) \varphi(y) dy &= \int_{\mathbb{R}^d} G(s, x, z) \int_{\mathbb{R}^d} G(t, z, y) \varphi(y) dy dz = \\ &= \int_{\mathbb{R}^d} \varphi(y) dy \int_{\mathbb{R}^d} G(s, x, z) G(t, z, y) dz. \end{aligned}$$

Then relation (13) is proved because the function  $\varphi$  is an arbitrary bounded continuous one.

Next, we get  $\int_{\mathbb{R}^d} G(t, x, y) dy \equiv 1$  from (2) and (3), because the equalities

$$\int_{\mathbb{R}^d} g(t, x, y) dy = 1 \quad \text{and} \quad \int_{\mathbb{R}^d} V_0(t, x, y) dy = \left( \mathbf{B}_x \int_{\mathbb{R}^d} g(t, x, y) dy, e(x) \right) = 0$$

for all  $t > 0$ ,  $x \in \mathbb{R}^d$  are obvious, and the uniqueness of the solution of equation (3) leads us to the identity  $\int_{\mathbb{R}^d} V(t, x, y) dy \equiv 0$ .  $\square$

*Remark 2.2.* The family of operators  $(T_t)_{t>0}$  defined for any bounded continuous function  $\varphi$  on  $\mathbb{R}^d$  by the equality  $T_t \varphi(x) = \int_{\mathbb{R}^d} G(t, x, y) \varphi(y) dy$ ,  $t > 0$ ,  $x \in \mathbb{R}^d$ , indeed constitutes a semigroup generated by the operator  $\mathbf{A} + (a(x), \mathbf{B})$ . But, there is no Markov process in  $\mathbb{R}^d$  corresponding to this semigroup because it does not preserve the property of a function to take on only non-negative values (see, for example, [1]).

### 3. THE CAUCHY PROBLEM

First, let the function  $a$  be smooth enough. For the simplicity we suppose that  $a \in C_0^\infty(\mathbb{R}^d)$  (this is the space of all  $\mathbb{R}^d$ -valued infinitely differentiable functions on  $\mathbb{R}^d$  with compact support). Thus, the function

$$\begin{aligned} U(t, x) &= \int_{\mathbb{R}^d} \varphi(y) G(t, x, y) dy = \\ &= \int_{\mathbb{R}^d} \varphi(y) g(t, x, y) dy + \int_0^t d\tau \int_{\mathbb{R}^d} g(t - \tau, x, y) \int_{\mathbb{R}^d} V(\tau, y, z) \varphi(z) dz |a(y)| dy \end{aligned}$$

is the unique (in the class of functions that tends to zero at infinity) solution of the Cauchy problem (8) with  $f(t, x) = |a(x)| \int_{\mathbb{R}^d} V(t, x, z) \varphi(z) dz$ .

Now we note that  $V(t, x, y) = (\mathbf{B}_x G(t, x, y), e(x))$ . Then

$$f(t, x) = \int_{\mathbb{R}^d} (\mathbf{B}_x G(t, x, z), a(x)) \varphi(z) dz = (a(x), \mathbf{B}_x U(t, x))$$

and the function  $U(t, x)$  is a solution of the Cauchy problem

$$(15) \quad \begin{cases} \frac{\partial u(t, x)}{\partial t} = \mathbf{A}_x u(t, x) + (a(x), \mathbf{B}_x u(t, x)), & t > 0, x \in \mathbb{R}^d, \\ \lim_{t \rightarrow 0+} u(t, x) = \varphi(x), & x \in \mathbb{R}^d \end{cases}$$

for an arbitrary continuous bounded function  $(\varphi(x))_{x \in \mathbb{R}^d}$ .

The next statement will allow us to construct a generalized solution of the Cauchy problem.

**Theorem 3.1.** *Let  $a$  and  $\tilde{a}$  be given functions that satisfy the conditions of Theorem 2.1. Denote by  $G$  and  $\tilde{G}$  the solutions of (1) corresponding to the functions  $a$  and  $\tilde{a}$ ,*

respectively. Then the inequality

$$|G(t, x, y) - \tilde{G}(t, x, y)| \leq H_T \|a - \tilde{a}\|_p \frac{t^{1 - \frac{d}{\alpha p}}}{(t^{\frac{1}{\alpha}} + |y - x|)^{d + \alpha - 1}}$$

(or  $|G(t, x, y) - \tilde{G}(t, x, y)| \leq H_T \|a - \tilde{a}\|_\infty \frac{t}{(t^{\frac{1}{\alpha}} + |y - x|)^{d + \alpha - 1}}$ , if  $p = +\infty$ )

is held on each domain  $(0, T] \times \mathbb{R}^d \times \mathbb{R}^d$  for  $T < +\infty$ , where the positive constant  $H_T$  depends on  $c, \alpha, \|a\|_p, \|\tilde{a}\|_p$  and  $T$ .

*Proof.* We will consider the case of finite values of  $p$ . The case  $p = +\infty$  is similar to this one.

It is easy to see that

$$(16) \quad G(t, x, y) - \tilde{G}(t, x, y) = \int_0^t d\tau \int_{\mathbb{R}^d} g(t - \tau, x, z) W(\tau, z, y) dz,$$

where  $W(\tau, z, y) = V(\tau, z, y)|a(z)| - \tilde{V}(\tau, z, y)|\tilde{a}(z)|$  and the functions  $V$  and  $\tilde{V}$  are solutions of equation (3) with the functions  $a$  and  $\tilde{a}$ , respectively. We can write down the following equality

$$(17) \quad W(t, x, y) = W_0(t, x, y) + |a(x)| \int_0^t d\tau \int_{\mathbb{R}^d} V_0(t - \tau, x, z) W(\tau, z, y) dz + \int_0^t d\tau \int_{\mathbb{R}^d} W_0(t - \tau, x, z) \tilde{V}(\tau, z, y) |\tilde{a}(z)| dz,$$

taking into account equality (3), where  $W_0(t, x, y) = (\mathbf{B}_x g(t, x, y), a(x) - \tilde{a}(x))$ .

Let us estimate the first and the third items on the right-hand side of equality (17). The following inequality

$$|W_0(t, x, y)| \leq |\mathbf{B}_x g(t, x, y)| |a(x) - \tilde{a}(x)| \leq \frac{N}{c\alpha} \frac{|a(x) - \tilde{a}(x)|}{(t^{1/\alpha} + |y - x|)^{d + \alpha - 1}}$$

is easily derived from formulas (4) and (9) for  $x \in \mathbb{R}^d, y \in \mathbb{R}^d, t > 0$ . Using inequalities (7), (10) and the previous inequality one can show that for  $x \in \mathbb{R}^d, y \in \mathbb{R}^d, t \in (0, T]$  and every  $T > 0$

$$\left| \int_0^t d\tau \int_{\mathbb{R}^d} W_0(t - \tau, x, z) \tilde{V}(\tau, z, y) |\tilde{a}(z)| dz \right| \leq K_T |a(x) - \tilde{a}(x)| \frac{t^{1/\alpha}}{(t^{1/\alpha} + |y - x|)^{d + \alpha - 1}},$$

where  $K_T$  is some positive constant, which depends on  $T$ , maybe.

Thus, we can write down the following inequality

$$(18) \quad |W(t, x, y)| \leq Q_T \frac{|a(x) - \tilde{a}(x)|}{(t^{1/\alpha} + |y - x|)^{d + \alpha - 1}} + \frac{N}{c\alpha} \int_0^t d\tau \int_{\mathbb{R}^d} \frac{|W(\tau, z, y)|}{((t - \tau)^{1/\alpha} + |z - x|)^{d + \alpha - 1}} dz$$

that holds true for  $x \in \mathbb{R}^d, y \in \mathbb{R}^d, t \in (0, T]$  and every  $T > 0$ , where  $Q_T > 0$  is some constant, which maybe depends on  $T$ .

Iterating inequality (18) we obtain for  $x \in \mathbb{R}^d, y \in \mathbb{R}^d, t \in (0, T]$  and every  $T > 0$

$$(19) \quad |W(t, x, y)| \leq \sum_{k=0}^{\infty} R_k(t, x, y),$$

where  $R_0(t, x, y) = Q_T \frac{|a(x) - \tilde{a}(x)|}{(t^{1/\alpha} + |y - x|)^{d + \alpha - 1}}$  and for  $k \geq 1$  the following recurrence

relation  $R_k(t, x, y) = \frac{N}{c\alpha} \int_0^t d\tau \int_{\mathbb{R}^d} \frac{R_{k-1}(\tau, z, y)}{((t - \tau)^{1/\alpha} + |z - x|)^{d + \alpha - 1}} dz$  holds.

Using Hölder's inequality and inequality (7) one can show by induction on  $k$  that the function  $R_k$  for  $k = 1, 2, \dots$  satisfies the inequalities

$$\begin{aligned} 0 \leq R_k(t, x, y) &\leq Q_T \left( \frac{N}{c\alpha} \right)^k C^{k-1/p} \left( 2B \left( 1, \frac{p-d-\alpha}{\alpha(p-1)} \right) \right)^{1-1/p} \times \\ &\quad \times \left( B \left( \frac{1}{\alpha}, 1 + \frac{p-d}{\alpha p} \right) + B \left( 1, 1 + \frac{2p-d}{\alpha p} \right) \right) \times \dots \\ &\quad \times \left( B \left( \frac{1}{\alpha}, 1 + \frac{(k-1)p-d}{\alpha p} \right) + B \left( 1, 1 + \frac{kp-d}{\alpha p} \right) \right) \times \\ &\quad \times \frac{t^{(kp-d)/(\alpha p)}}{(t^{1/\alpha} + |y-x|)^{d+\alpha-1}} \|a - \tilde{a}\|_p. \end{aligned}$$

Hence, we conclude that the series in inequality (19) converges uniformly in  $x \in \mathbb{R}^d$ ,  $y \in \mathbb{R}^d$  and locally uniformly in  $t > 0$ . Therefore, the following inequality

$$|W(t, x, y)| \leq M_T \frac{\|a - \tilde{a}\|_p}{(t^{1/\alpha} + |y-x|)^{d+\alpha-1}} t^{\frac{p-d}{\alpha p}} + Q_T \frac{|a(x) - \tilde{a}(x)|}{(t^{1/\alpha} + |y-x|)^{d+\alpha-1}}$$

holds for  $x \in \mathbb{R}^d$ ,  $y \in \mathbb{R}^d$ ,  $t \in (0, T]$  and every  $T > 0$ , where  $M_T$  and  $Q_T$  are some positive constants, which maybe depend on  $T$ .

Some not difficult calculations using formulas (6),(7), (16) and Hölder's inequality lead us to the assertion of the theorem.  $\square$

**Corollary 3.1.** *Let  $\varphi \in C_b(\mathbb{R}^d)$  and  $G, \tilde{G}$  be as in Theorem 2.1. Put*

$$U(t, x) = \int_{\mathbb{R}^d} G(t, x, y)\varphi(y) dy, \quad \tilde{U}(t, x) = \int_{\mathbb{R}^d} \tilde{G}(t, x, y)\varphi(y) dy.$$

*Then the following inequality  $|U(t, x) - \tilde{U}(t, x)| \leq L_T \sup_y |\varphi(y)| \|a - \tilde{a}\|_p$  is held for  $x \in \mathbb{R}^d$ ,  $0 < t \leq T$ . Here  $L_T$  is some positive constant, that maybe depends of  $T$ .*

Now, let  $a(x)$  be a given  $\mathbb{R}^d$ -valued function on  $\mathbb{R}^d$  satisfying the condition  $\|a\|_p < \infty$  for some  $p > d + \alpha$ . Then there exists a sequence of functions  $a_n \in C_0^\infty(\mathbb{R}^d)$ , such that  $\|a_n - a\|_p \rightarrow 0$  as  $n \rightarrow \infty$ . According to Corollary 3.1, we can defined the function  $U(t, x)$  by the equality  $U(t, x) = \lim_{n \rightarrow \infty} U_n(t, x)$ , where  $U_n(t, x)$  is the solution of the Cauchy problem (15) corresponding to the function  $a_n$ . The statement of Theorem 3.1 means that  $U(t, x) = \int_{\mathbb{R}^d} G(t, x, y)\varphi(y) dy$ , where  $G(t, x, y)$  is the perturbation (corresponding to the function  $a$ ) of the transition probability density of the symmetric stable process (see Definition 1.1). We say exactly in this sense that the function  $U(t, x)$  is a generalized solution of the Cauchy problem (15).

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